

LED Driver with I²C Compatible and 3-wire Serial Interface for 8×16 LEDs in Dot Matrix

BU16501KS2

General Description

BU16501KS2 is "Matrix LED Driver" that is the most suitable for Home Appliance.

It can control 8x16 (128 dot) LED Matrix by internal 8-channel PMOS SWs and 16-channel LED drivers. It can control the brightness in each dot by the setting of the internal register.

It supports SPI and I²C interface.

Key Specifications

Operating power supply voltage range: 2.7V to 5.5V
 Oscillator frequency: 1.2MHz (Typ.)
 Operating temperature range: -40°C to +85°C

Package(s) SQFP-T52M SQFP-T52 **W(Typ) x D(Typ) x H(Max)** 12.00mm x 12.00mm x 1.60mm 12.00mm x 12.00mm x 1.50mm



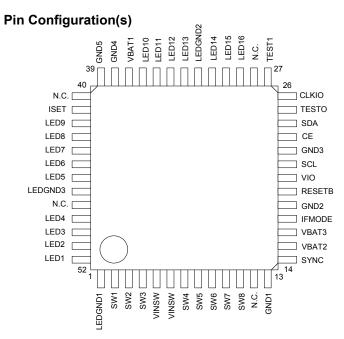
Features

- LED Matrix driver (8x16)
 - It has 8-channel PMOS SWs and 16-channel current drivers with 1/8 TDM timing driven sequentially.
 - Put ON/OFF (for every dot)
 - The current drivers can drive from 0 to 20.00mA current with "16" steps(for every dot)
 - The current drivers can drive maximum 42.5mA/Line (ISET=47kΩ)
 - 64 steps of the luminance control by PWM (common setting for all dots)
- Interface
 - SPI and I²C BUS FS mode (max 400 kHz) Compability.
 - For l²C mode, l²C Device address is selectable (74h or 75h).
- Thermal Shutdown

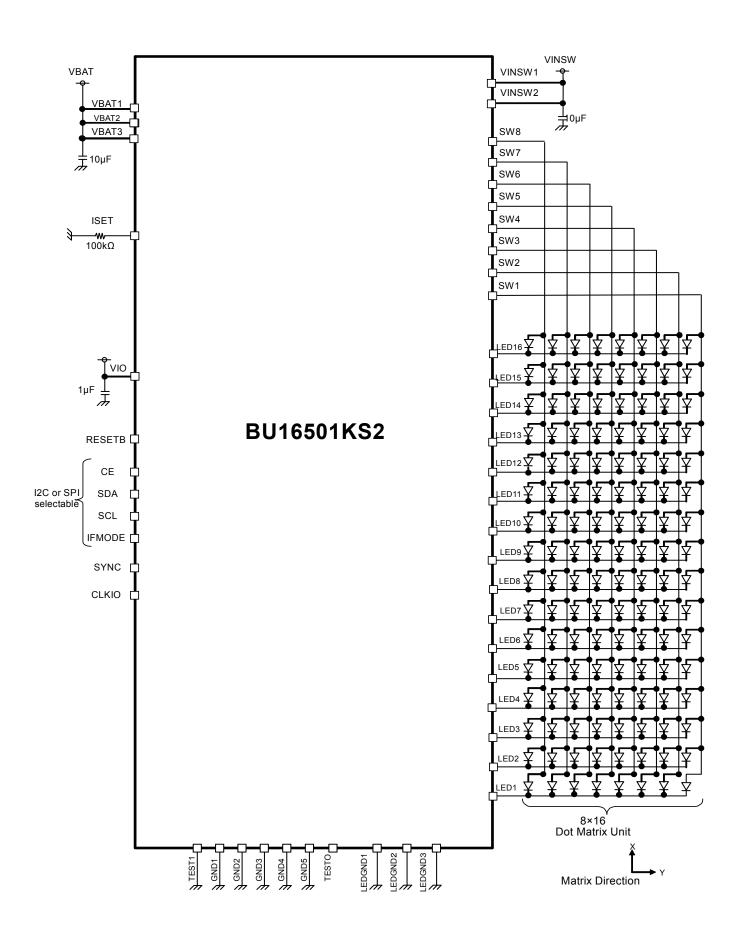
Applications

Mobile phone, portable device, home electrical appliance, and general consumer equipment. Device provided with LED display application. LED display.

Amusement, Traffic Signboards, hobby, etc.



Typical Application Circuit(s)



Pin Description(s)

Description(s)											
	D'. N.		Pull	Unused	ESD	Diode	F	Equivalent			
No	Pin Name	I/O	down	processing setting	For Power	For Ground	Functions	Circuit			
1	LEDGND1	-	-	-	VBAT	-	Ground	В			
2	SW1	0	-	VINSW	VINSW	GND	P-MOS SW1 output	С			
3	SW2	0	-	VINSW	VINSW	GND	P-MOS SW2 output	С			
4	SW3	0	-	VINSW	VINSW	GND	P-MOS SW3 output	С			
5	VINSW1	1	_	_	_	GND	Power supply for SW1-8	Α			
6	VINSW2	1	-	-	-	GND	Power supply for SW1-8	Α			
7	SW4	0	-	VINSW	VINSW	GND	P-MOS SW4 output				
8	SW5	0	-	VINSW	VINSW	GND	P-MOS SW5 output	С			
9	SW6	0	-	VINSW	VINSW	GND	P-MOS SW6 output	С			
10	SW7	0	-	VINSW	VINSW	GND	P-MOS SW7 output	С			
11	SW8	0	-	VINSW	VINSW	GND	P-MOS SW8 output	С			
12	NC	-	-	-	-	-	-	-			
13	GND1	-	-	-	VBAT	-	Ground	В			
14	SYNC	- 1	-	GND	VBAT	GND	External synchronous input pin	D			
15	VBAT2	ı	-	-	-	GND	Battery is connected	Α			
16	VBAT3		-	-	-	GND	Battery is connected	Α			
17	IFMODE	I	-	GND	VBAT	GND	I ² C/SPI select pin (L: I ² C, H: SPI)	D			
18	GND2	-	-	-	VBAT	-	Ground	В			
19	RESETB	-	-	GND	VBAT	GND	Reset input pin (L: reset, H: reset cancel)	D			
20	VIO	-	-	-	VBAT	GND	I/O Power supply is connected	1			
21	SCL	1	-	_	VBAT	GND	SPI, I ² C CLK input pin	D			
22	GND3	-	-	-	VBAT	-	Ground	В			
							SPI enable pin(H;Enable), or	D			
23	CE	- 1	-	GND	VBAT	GND	I ^C C slave address selection (L: 74h, H: 75h)				
24	SDA	I/O	-	-	VBAT	GND	SPI DATA input / I ² C DATA input-output pin	F			
25	TESTO	0	-	OPEN	VBAT	GND	Test output pin1	G			
26	CLKIO	I/O	500Ω	OPEN	VBAT	GND	Reference CLK input / output pin	М			
27	TEST1	- 1	94kΩ	GND	VBAT	GND	Test input pin 1	Е			
28	NC	-	-	-	-	-	-	-			
29	LED16	0	-	GND	-	GND	LED16 driver output	K			
30	LED15	0	-	GND	-	GND	LED15 driver output	K			
31	LED14	0	-	GND	-	GND	LED14 driver output	K			
32	LEDGND2	-	-	-	VBAT	-	Ground	В			
33	LED13	0	-	GND	-	GND	LED13 driver output	K			
34	LED12	0	-	GND	-	GND	LED12 driver output	K			
35	LED11	0	-	GND	-	GND	LED11 driver output	K			
36	LED10	0	-	GND	-	GND	LED10 driver output	K			
37	VBAT1	-	-	-	- VDAT	GND	Battery is connected	A			
38	GND4	-	-	-	VBAT	-	Ground	В			
39	GND5	-	-	-	VBAT -	-	Ground	В			
40	NC	-	-	-			FD Constant Current Division Current and Current	-			
41	ISET	-	-	- CND	VBAT	GND	LED Constant Current Driver Current setting pin	J			
42	LED9	0		GND	-	GND	LED9 driver output	K			
43	LED8	0	_	GND	-	GND	LEDZ driver output	K			
44 45	LED7 LED6	0	_	GND	-	GND	LED7 driver output	K			
46	LED6	0	_	GND GND	-	GND GND	LED6 driver output LED5 driver output	K			
46	LEDGND3	-	_	GND -	- VBAT	- GND	Ground	В			
48	NC						Crownu				
48	LED4	0	-	- GND	-	- GND	LED4 driver output	- K			
50	LED4	0	-	GND	-	GND	LED3 driver output	K			
51	LED3	0	-	GND	-	GND	LED2 driver output	K			
52	LED2	0		GND				K			
52	LEUÏ	U	-	טאט	-	GND	LED1 driver output	ĸ			

Pin ESD Type

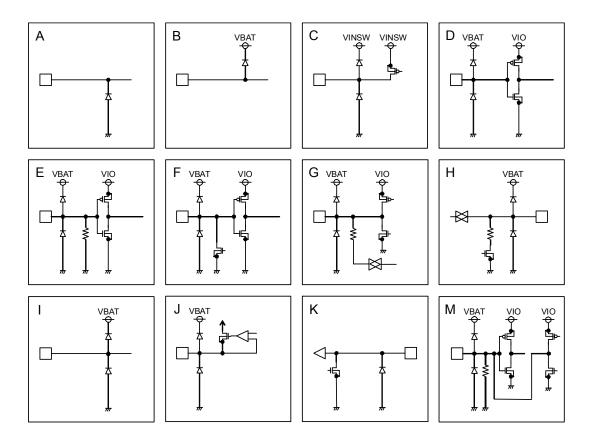


Figure 1. Pin ESD Type

Absolute Maximum Ratings (Ta=25°C)

Parameter	Symbol	Limits	Unit
Terminal voltage	VMAX	-0.3 to +7	V
Power Dissipation (note1)	Pd	1.30	W
Operating Temperature Range	Topr	-40 to +85	°C
Storage Temperature Range	Tstg	-55 to +125	°C

Power dissipation deleting is 13mW/°C, when it's used in over 25°C (ROHM's standard one layer board has been mounted.)
The power dissipation of the IC has to be less than the one of the package. (Note1)

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Recommended Operating Ratings (Ta=-40 to 85°C)

Parameter	Symbol	Limits	Unit
VBAT input voltage	VBAT	2.7 to 5.5	V
VINSW input voltage	VINSW	2.7 to 5.5	V
VIO pin voltage	VIO	1.65 to 5.5	V

Electrical Characteristics

(Unless otherwise specified, Ta=25°C, VBAT=5.0V, VINSW=5.0V, VIO=5.0V)

Parameter	Symbol		Limit		Unit	Condition
Parameter	Symbol	Min	Тур	Max	Unit	Condition
[Circuit Current]	-	I .				
VBAT Circuit current 1	IBAT1	-	0	3.0	μΑ	RESETB=0V, VIO=0V
VBAT Circuit current 2	IBAT2	-	0.7	5.0	μΑ	RESETB=0V, VIO=5.0V
VBAT Circuit current 3	IBAT3	-	2.1	3.5	mA	When LED1-16 are active with 10.67mA settings
[UVLO]						
UVLO Threshold	VUVLO	-	2.1	2.5	V	VBAT falling
UVLO Hysteresis	VHYUVLO	50	-	-	mV	
[LED Driver] (LED1-16)						
Marian	ILEDMax1	-	20.00	-	mA	LED1-16 ,ISET=100kΩ
Maximum output current	ILEDMax2	-	42.50	-	mA	LED1-16 ,ISET=47kΩ
Output current	ILED	-7.0	-	+7.0	%	I=10.67mA setting, VLED=1V ISET=100kΩ
LED current Matching	ILEDMT	-	-	5	%	ILEDMT= (ILEDMax-ILEDMin)/(ILEDMax+ILEDMin) I=10.67mA setting, VLED=1V, ISET=100kΩ
Driver pin voltage range	VLED1	0.2	-	VBAT - 1.4	V	LED1-16 ,ISET=100kΩ
LED OFF Leak current	ILKLED	-	-	1.0	μΑ	
[PMOS switch]						
Leak current at OFF	ILEAKP	-	-	1.0	μA	
Resistor at ON	RonP	-	1.0	-	Ω	Isw=160mA, VINSW=5.0V
[OSC]						
OSC frequency	fosc	0.96	1.2	1.44	MHz	
[CE, SYNC, IFMODE]						
L level input voltage	VIL1	-0.3	-	0.25 x VIO	V	
H level input voltage	VIH1	0.75 x VIO	-	VIO +0.3	V	
input current	lin1	-	0	1	μA	Input voltage = from (0.1 x VIO) to (0.9 x VIO)

Electrical Characteristics - continued

Danamatan	0		Limit		11:4	O and distinct
Parameter	Symbol	Min	Тур	Max	Unit	Condition
[SDA, SCL]						
L level input voltage	VIL2	-0.3	-	0.25×VIO	V	
H level input voltage	VIH2	0.75×VIO	-	VIO+0.3	V	
Input hysteresis	Vhys	0.05×VIO	-	-	V	
L level output voltage (for SDA pin)	VOL2	-	-	0.3	V	IOL=3mA
Input current	lin2	-3	-	3	μA	Input voltage = from (0.1 x VIO) to (0.9 x VIO)
[RESETB]					•	
L level input voltage	VIL3	-0.3	-	0.25×VIO	V	
H level input voltage	VIH3	0.75×VIO	-	VIO+0.3	V	
Input current	lin3	-	0	1	μA	Input voltage = from (0.1 x VIO) to (0.9 x VIO)
【CLKIO(output)】						
L level output voltage	VOL1	-	-	0.4	V	IOL=2mA
H level output voltage	VOH1	VIO-0.4	-	-	V	IOH=-2mA
[CLKIO(input)]	•					
L level input voltage	VIL4	-0.3	-	0.25×VIO	V	
H level input voltage	VIH4	0.75×VIO	-	VIO+0.3	V	
Input current	lin4	-	10	20	μA	Input voltage =5.0V

(Unless otherwise specified, Ta=25°C, VBAT=5.0V, VINSW=5.0V, VIO=5.0V)

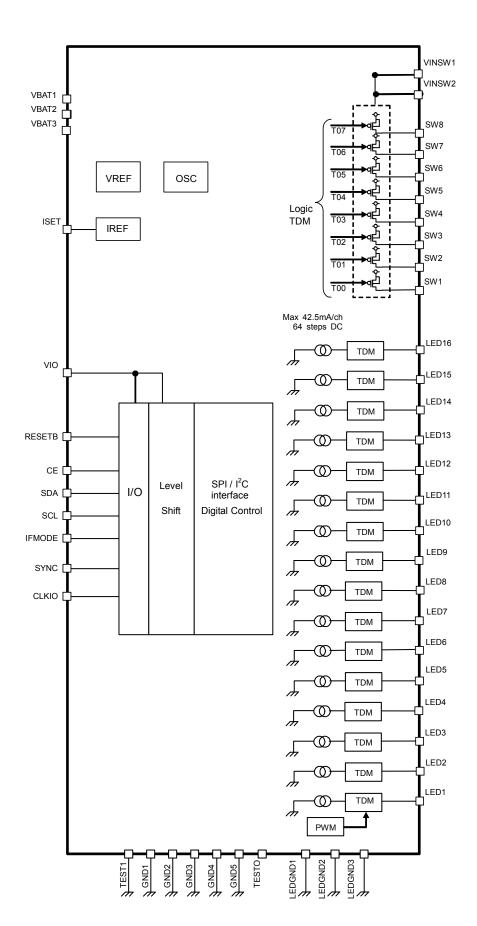
Doromotor	Cymbol		Limit		l lmi4	Condition		
Parameter	Symbol	Min	Тур	Max	Unit	Condition		
SCL cycle time	tscyc	76	-	-	ns			
H period of SCL cycle	Twhc	35	-	-	ns			
L period of SCL cycle	Twlc	35	-	-	ns			
SDA setup time	Tss	38	-	=	ns			
SDA hold time	Tsh	38	-	=	ns			
Write interval		38	-	=	ns			
Write interval	Tcsw	2.1	-	-	μs	(Note 1)		
(after RAM accsess)		ECLK x 2	-	-	S	(Note 2)		
CE setup time	Tcss	55	-	-	ns			
CE hold time	Tcgh	48	-	-	ns			

(Note 1) When it used internal clock.
(Note 2) When it used external clock. (ECLK means the cycle of external clock)

(Unless otherwise specified Ta=25°C, VBAT=5.0V, VINSW=5.0V, VIO=5.0V)

(Unless otherwise specified, Ta=25 °C, VBAT	(Unless otherwise specified, Ta=25°C, VBAT=5.0V, VINSW=5.0V, VIO=5.0V)											
Parameter	Cymbol	Sta	andard-mo	ode	F	Unit						
Parameter	Symbol	Min	Тур	Max	Min	Тур	Max	Unit				
[I ² C BUS format]												
SCL clock frequency	fscl	0	-	100	0	-	400	kHz				
LOW period of the SCL clock	tLOW	4.7	-	-	1.3	-	-	μs				
HIGH period of the SCL clock	thigh	4.0	-	-	0.6	-	-	μs				
Hold time (repeated) START condition After this period, the first clock is generated	thd;sta	4.0	-	-	0.6	-	-	μs				
Set-up time for a repeated START condition	tsu;sta	4.7	-	-	0.6	-	ı	μs				
Data hold time	thd;dat	0	-	3.45	0	-	0.9	μs				
Data set-up time	tsu;dat	250	-	-	100	-	-	ns				
Set-up time for STOP condition	tsu;sto	4.0	-	-	0.6	-	-	μs				
Bus free time between a STOP and START condition	tBUF	4.7	-	-	1.3	-	-	μs				

Block Diagram



Serial Interface

- 1. SPI format
 - · When IFMODE is set to "H", it can interface with SPI format.
 - The serial interface is four terminals (serial clock terminal (SCL), serial data input terminal (SDA), and chip selection input terminal (CE)).

(1) Write operation

- · Data is taken into an internal shift register with rising edge of SCL. (Max of the frequency is 13MHz.)
- The receive data becomes enable in the "H" section of CE. (Active "H".)
- The transmit data is forwarded (with MSB-First) in the order of write command "0"(1bit), the control register address (7bit) and data (8bit).

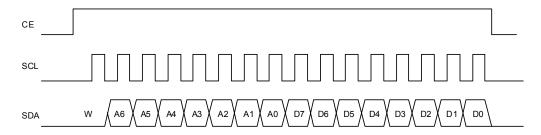


Figure 2. Writing format

(2) Timing diagram

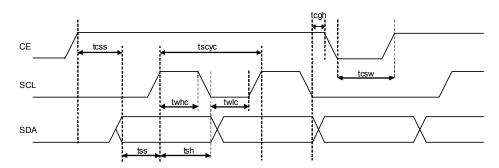


Figure 3. Timing diagram (SPI format)

2. I2C BUS format

When IFMODE is set to "L", it can interface with I2C BUS format.

(1) Slave address

CE	A7	A6	A5	A4	A3	A2	A1	R/W
L	1	1	1	0	1	0	0	0
Н	1	1	1	0	1	0	1	U

(2) Bit Transfer

SCL transfers 1-bit data during H. During H of SCL, SDA cannot be changed at the time of bit transfer. If SDA changes while SCL is H, START conditions or STOP conditions will occur and it will be interpreted as a control signal.

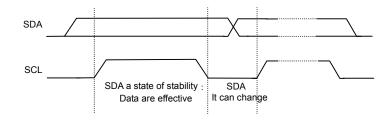


Figure 4. Bit transfer (I²C format)

Serial Interface - continued

(3) START and STOP condition

When SDA and SCL are H, data is not transferred on the I²C- bus. This condition indicates, if SDA changes from H to L while SCL has been H, it will become START (S) conditions, and an access start, if SDA changes from L to H while SCL has been H, it will become STOP (P) conditions and an access end.

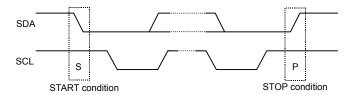


Figure 5. START/STOP condition (I²C format)

(4) Acknowledge

It transfers data 8 bits each after the occurrence of START condition. A transmitter opens SDA after transfer 8bits data, and a receiver returns the acknowledge signal by setting SDA to L.

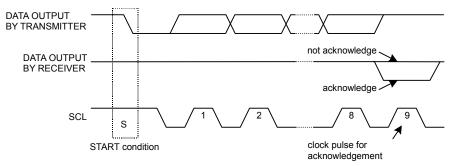
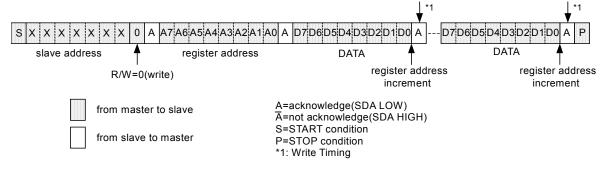


Figure 6. Acknowledge (I²C format)

(5) Writing protocol

A register address is transferred by the next 1 byte that transferred the slave address and the write-in command. The 3rd byte writes data in the internal register written in by the 2nd byte, and after 4th byte or, the increment of register address is carried out automatically. However, when a register address turns into the last address (40h), it is set to 00h by the next transmission. After the transmission end, the increment of the address is carried out.



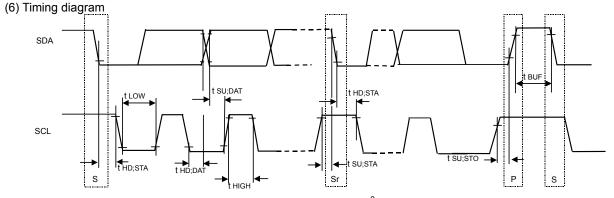


Figure 7. Timing diagram (I²C C format)

Register List

(Note) Please be sure to write "0" in the register which is not assigned. It is prohibition to write data to the address which is not assigned.

Control register

	- 3										
Address	default	D7	D6	D5	D4	D3	D2	D1	D0	Block	Remark
00h	00h	-	-	-	-	-	-	-	SFTRST	RESET	Software Reset
01h	00h	-	-	-	ı	OSCEN	-	-	-	OSC	OSC ON/OFF control
11h	00h	LED8ON	LED7ON	LED6ON	LED5ON	LED4ON	LED3ON	LED2ON	LED10N	LED	LED1-8 Enable
12h	00h	LED16ON	LED15ON	LED14ON	LED13ON	LED12ON	LED110N	LED10ON	LED9ON	driver	LED9-16 Enable
20h	00h	-	-			PWMS	ET[5:0]			PWM	LED1-16 PWM setting
21h	00h	CLKSE	EL[1:0]	-	1	SYNCACT	SYNCON	CLKOUT	CLKIN	CLK	CLK selection, SYNC operation control
2Dh	00h	-	-	-	ı	-	PWMEN	-	-		PWM ON/OFF setting
30h	00h	-	-	-	1	-	-	-	START	MATRIX	LED matrix control
31h	00h	-	-	-	-	-	-	-	CLRA		Matrix data clear
7Fh	00h	-	-	-	-	-	-	-	RMCG	RMAP	Resistor map change

Pattern register

Pattern re	egister					
Address	default	D7 D6 D5 D4	D3 D2 D1 D0	Block	R/W	Remark
01h	00h	ILED01SET[3:0]	ILED00SET[3:0]	MATRIX	W	Data for Matrix 01/00
02h	00h	ILED03SET[3:0]	ILED02SET[3:0]	DATA	W	Data for Matrix 03/02
03h	00h	ILED05SET[3:0]	ILED04SET[3:0]		W	Data for Matrix 05/04
04h	00h	ILED07SET[3:0]	ILED06SET[3:0]		W	Data for Matrix 07/06
05h	00h	ILED11SET[3:0]	ILED10SET[3:0]		W	Data for Matrix 11/10
06h	00h	ILED13SET[3:0]	ILED12SET[3:0]		W	Data for Matrix 13/12
07h	00h	ILED15SET[3:0]	ILED14SET[3:0]		W	Data for Matrix 15/14
08h	00h	ILED17SET[3:0]	ILED16SET[3:0]		W	Data for Matrix 17/16
09h	00h	ILED21SET[3:0]	ILED20SET[3:0]		W	Data for Matrix 21/20
0Ah	00h	ILED23SET[3:0]	ILED22SET[3:0]		W	Data for Matrix 23/22
0Bh	00h	ILED25SET[3:0]	ILED24SET[3:0]		W	Data for Matrix 25/24
0Ch	00h	ILED27SET[3:0]	ILED26SET[3:0]		W	Data for Matrix 27/26
0Dh	00h	ILED31SET[3:0]	ILED30SET[3:0]		W	Data for Matrix 31/30
0Eh	00h	ILED33SET[3:0]	ILED32SET[3:0]		W	Data for Matrix 33/32
0Fh	00h	ILED35SET[3:0]	ILED34SET[3:0]		W	Data for Matrix 35/34
10h	00h	ILED37SET[3:0]	ILED36SET[3:0]		W	Data for Matrix 37/36
11h	00h	ILED41SET[3:0]	ILED40SET[3:0]		W	Data for Matrix 41/40
12h	00h	ILED43SET[3:0]	ILED42SET[3:0]		W	Data for Matrix 43/42
13h	00h	ILED45SET[3:0]	ILED44SET[3:0]		W	Data for Matrix 45/44
14h	00h	ILED47SET[3:0]	ILED46SET[3:0]		W	Data for Matrix 47/46
15h	00h	ILED51SET[3:0]	ILED50SET[3:0]		W	Data for Matrix 51/50
16h	00h	ILED53SET[3:0]	ILED52SET[3:0]		W	Data for Matrix 53/52
17h	00h	ILED55SET[3:0]	ILED54SET[3:0]		W	Data for Matrix 55/54
18h	00h	ILED57SET[3:0]	ILED56SET[3:0]		W	Data for Matrix 57/56
19h	00h	ILED61SET[3:0]	ILED60SET[3:0]		W	Data for Matrix 61/60
1Ah	00h	ILED63SET[3:0]	ILED62SET[3:0]		W	Data for Matrix 63/62
1Bh	00h	ILED65SET[3:0]	ILED64SET[3:0]		W	Data for Matrix 65/64
1Ch	00h	ILED67SET[3:0]	ILED66SET[3:0]		W	Data for Matrix 67/66
1Dh	00h	ILED71SET[3:0]	ILED70SET[3:0]		W	Data for Matrix 71/70
1Eh	00h	ILED73SET[3:0]	ILED72SET[3:0]		W	Data for Matrix 73/72
1Fh	00h	ILED75SET[3:0]	ILED74SET[3:0]		W	Data for Matrix 75/74
20h	00h	ILED77SET[3:0]	ILED76SET[3:0]		W	Data for Matrix 77/76
21h	00h	ILED81SET[3:0]	ILED80SET[3:0]		W	Data for Matrix 81/80
22h	00h	ILED83SET[3:0]	ILED82SET[3:0]		W	Data for Matrix 83/82
23h	00h	ILED85SET[3:0]	ILED84SET[3:0]		W	Data for Matrix 85/84
24h	00h	ILED87SET[3:0]	ILED86SET[3:0]		W	Data for Matrix 87/86
25h	00h	ILED91SET[3:0]	ILED90SET[3:0]		W	Data for Matrix 91/90
26h	00h	ILED93SET[3:0]	ILED92SET[3:0]		W	Data for Matrix 93/92
27h	00h	ILED95SET[3:0]	ILED94SET[3:0]		W	Data for Matrix 95/94
28h	00h	ILED97SET[3:0]	ILED96SET[3:0]		W	Data for Matrix 97/96
29h	00h	ILEDA1SET[3:0]	ILEDA0SET[3:0]		W	Data for Matrix A1/A0
2Ah	00h	ILEDA3SET[3:0]	ILEDA2SET[3:0]		W	Data for Matrix A3/A2
2Bh	00h	ILEDA5SET[3:0]	ILEDA4SET[3:0]		W	Data for Matrix A5/A4
2Ch	00h	ILEDA7SET[3:0]	ILEDA6SET[3:0]		W	Data for Matrix A7/A6
2Dh	00h	ILEDB1SET[3:0]	ILEDB0SET[3:0]		W	Data for Matrix B1/B0
2Eh	00h	ILEDB3SET[3:0]	ILEDB2SET[3:0]		W	Data for Matrix B3/B2
2Fh	00h	ILEDB5SET[3:0]	ILEDB4SET[3:0]		W	Data for Matrix B5/B4

Pattern register - continued

Address	default	D7 D6 D5 D4	D3 D2 D1 D0	Block	R/W	Remark							
30h	00h	ILEDB7SET[3:0]	ILEDB6SET[3:0]	MATRIX	W	Data for Matrix B7/B6							
31h	00h	ILEDC1SET[3:0]	ILEDC0SET[3:0]	DATA	W	Data for Matrix C1/C0							
32h	00h	ILEDC3SET[3:0]	ILEDC2SET[3:0]		W	Data for Matrix C3/C2							
33h	00h	ILEDC5SET[3:0]	ILEDC4SET[3:0]		W	Data for Matrix C5/C4							
34h	00h	ILEDC7SET[3:0]	ILEDC6SET[3:0]		W	Data for Matrix C7/C6							
35h	00h	ILEDD1SET[3:0]	ILEDD0SET[3:0]		W	Data for Matrix D1/D0							
36h	00h	ILEDD3SET[3:0]	ILEDD2SET[3:0]		W	Data for Matrix D3/D2							
37h	00h	ILEDD5SET[3:0]	ILEDD4SET[3:0]		W	Data for Matrix D5/D4							
38h	00h	ILEDD7SET[3:0]	ILEDD6SET[3:0]		W	Data for Matrix D7/D6							
39h	00h	ILEDE1SET[3:0]	ILEDE0SET[3:0]		W	Data for Matrix E1/E0							
3Ah	00h	ILEDE3SET[3:0]	ILEDE2SET[3:0]		W	Data for Matrix E3/E2							
3Bh	00h	ILEDE5SET[3:0]	ILEDE4SET[3:0]		W	Data for Matrix E5/E4							
3Ch	00h	ILEDE7SET[3:0]	ILEDE6SET[3:0]		W	Data for Matrix E7/E6							
3Dh	00h	ILEDF1SET[3:0]	ILEDF0SET[3:0]		W	Data for Matrix F1/F0							
3Eh	00h	ILEDF3SET[3:0]	ILEDF2SET[3:0]		W	Data for Matrix F3/F2							
3Fh	00h	ILEDF5SET[3:0]	ILEDF4SET[3:0]		W	Data for Matrix F5/F4							
40h	00h	ILEDF7SET[3:0]	ILEDF6SET[3:0]		W	Data for Matrix F7/F6							

Register Map

Address 00h < Software Reset >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
00h	W	-	-	-	-	-	-	-	SFTRST
Initial value	00h	-	1	1	-	-	ı	ı	0

Bit 0 : SFTRST Software Reset "0" : Reset cancel

"1": Reset (All register initializing) SFTRST register return to 0 automatically.

Address 01h <OSC control >

, taa. 000 0 i		00110101							
Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
01h	W	-	-	-	-	OSCEN	-	-	-
Initial value	00h	-	-	-	-	0	-	-	-

Bit 3: OSCEN OSC block ON/OFF control

"0" : OFF (Initial)

"1" : ON

This register should not change into "1 " \rightarrow " 0" at the time of START (30h, D0) register ="1" setup (under lighting operation).

This register must be set to "0" after LED putting out lights ("START register = 0"), and please surely stop an internal oscillation circuit.

Address 11h < LED1-8 Enable >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
11h	W	LED8ON	LED7ON	LED6ON	LED5ON	LED4ON	LED3ON	LED2ON	LED10N
Initial value	00h	0	0	0	0	0	0	0	0

Bit 0: LED1ON LED1 ON/OFF setting

"0": LED1 OFF (initial)

"1": LED1 ON

Bit 1: LED2ON LED2 ON/OFF setting

"0": LED2 OFF (initial)

"1": LED2 ON

Bit 2: LED3ON LED3 ON/OFF setting

"0": LED3 OFF (initial)

"1": LED3 ON

Bit 3: LED4ON LED4 ON/OFF setting

"0": LED4 OFF (initial)

"1": LED4 ON

Bit 4: LED5ON LED5 ON/OFF setting

"0" : LED5 OFF (initial)

"1": LED5 ON

Bit 5: LED6ON LED6 ON/OFF setting

"0": LED6 OFF (initial)

"1": LED6 ON

Bit 6: LED7ON LED7 ON/OFF setting

"0": LED7 OFF (initial)

"1": LED7 ON

Bit 7: LED8ON LED8 ON/OFF setting

"0": LED8 OFF (initial)

"1" : LED8 ON

(Note) Current setting follows ILEDXXSET[3:0] register.

Address 12h < LED9-16 Enable >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
12h	W	LED16 ON	LED15 ON	LED14 ON	LED13 ON	LED12 ON	LED11 ON	LED10 ON	LED9 ON
Initial value	00h	0	0	0	0	0	0	0	0

Bit 0: LED9ON LED9 ON/OFF setting

"0": LED9 OFF (initial)

"1": LED9 ON

Bit 1: LED10ON LED10 ON/OFF setting

"0": LED10 OFF (initial)

"1": LED10 ON

Bit 2: LED11ON LED11 ON/OFF setting

"0": LED11 OFF (initial)

"1": LED11 ON

Bit 3: LED12ON LED12 ON/OFF setting

"0": LED12 OFF (initial)

"1": LED12 ON

Bit 4: LED13ON LED13 ON/OFF setting

"0" : LED13 OFF (initial)

"1": LED13 ON

Bit 5: LED14ON LED14 ON/OFF setting

"0": LED14 OFF (initial)

"1" : LED14 ON

Bit 6: LED15ON LED15 ON/OFF setting

"0": LED15 OFF (initial)

"1": LED15 ON

Bit 7: LED16ON LED16 ON/OFF setting

"0": LED16 OFF (initial)

"1": LED16 ON

(Note) Current setting follows ILEDXXSET[3:0] register.

Address 20h < LED1-16 PWM setting >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
20h	W	-	-			PWMS	ET [5:0]		
Initial value	00h	-	-	0	0	0	0	0	0

Bit 5-0 : PWMSET[5:0] LED1-16 PWM DUTY setting

"000000": 0/63=0%(initial) "000001": 1/63=1.59%

:

"100000" : 32/63=50.8%

:

"111110" : 62/63=98.4% "111111" : 63/63=100%

(Note)Please refer to Description of operation, chapter 2

Address 21h <Clock control / SYNC operation control>

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
21h	W	CLKSE	L[1:0]	-	-	SYNCACT	SYNCON	CLKOUT	CLKIN
Initial value	00h	0	0	-	-	0	0	0	0

Bit 0 : CLKIN Selection CLK for PWM control

"0": Internal OSC (initial)

"1": External CLK input (to CLKIO pin)

Bit 1 : CLKOUT Output CLK enable "0" : CLK is not output (initial)

"1": Output selected CLK from CLKIO pin

As for CLKIN & CLKOUT, setting change is forbidden under OSCEN (01h, D3) register ="1" and also under clock input to CLKIO terminal.

Bit 2: SYNCON SYNC operation enable

"0": Disable SYNC operation (initial)
"1": SYNC pin control LED driver ON/OFF

Bit 3: SYNCACT SYNC operation setting

"0": When SYNC pin is "L", LED drivers are ON (initial) "1": When SYNC pin is "H", LED drivers are ON

Bit 7-6 : CLKSEL[1:0] Select Clock Frequency

"00": 1.2MHz (initial)

"01" : 300kHz "10" : 150kHz "11" : 37.5kHz

Address 2Dh < PWM ON/OFF setting >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
2Dh	W	-	-	-	-	-	PWMEN	-	-
Initial value	00h	-	-	-	-	-	0	-	-

Bit 2: PWMEN PWM control at LED1-16 ON/OFF setting

"0": PWM operation is invalid (initial value)

"1": PWM operation is valid

(Note)Please refer to Description of operation, chapter 2

Address 30h < LED Matrix control >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
30h	W	-	-	-	-	-	-	-	START
Initial value	00h	-	-	-	-	-	-	-	0

Bit 0 : START Lighting/turning off bit of MATRIX LED(LED1-16)

"0": MATRIX LED (LED1-16) Lights out (initial)
"1": MATRIX LED (LED1-16) Lighting start

Address 31h < Matrix data clear >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
31h	W	-	-	-	-	-	-	-	CLRA
Initial value	00h	-	-	-	-	-	-	-	0

Bit 0 : CLRA Reset Pattern register

"0": Pattern register is not reset and writable (initial value)

"1": Pattern register is reset

(Note)CLRA register return to 0 automatically.

Address 7Fh < Register map change >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
7Fh	W	-	-	-	-	-	-	-	RMCG
Initial value	00h	-	-	-	-	-	-	-	0

Bit 0 : RMCG Change register map

"0": Control register is selected (initial value)

"1": Pattern register is selected

Address 01h-40h < Pattern register data >

Address (Index)	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
01-40h	W		ILEDXX	SET [3:0]		ILEDXXSET [3:0]			
Initial value	00h	0	0	0	0	0	0	0	0

Bit7-4/Bit 3-0 : ILEDXXSET[3:0] LED output current setting for Pattern matrix data

	ILEDxx8	SET[3:0]		電流値
0	0	0	0	0 [mA]
0	0	0	1	1/15 x ILEDmax [mA]
0	0	1	0	2/15 x ILEDmax [mA]
-			•	
•	•		•	1/15 x ILEDmax [mA]
•			•	Step
•	•		•	
1	1	0	1	13/15 x ILEDmax [mA]
1	1	1	0	14/15 x ILEDmax [mA]
1	1	1	1	15/15 x ILEDmax [mA]

example : ILEDmax=20mA (ISET=100 k Ω) , LED current setting as below.

"0000": 0.00mA "0001": 1.33mA "0010": 2.67mA "0011": 4.00mA "0100": 5.33mA "0101": 6.67mA "0110": 8.00mA "0111": 9.33mA

"1000": 10.67mA (initial value)

"1001": 12.00mA "1010": 13.33mA "1011": 14.67mA "1100": 16.00mA "1101": 17.33mA "1110": 18.67mA "1111": 20.00mA

(Note) In a SPI interface, the interval to the following access has regulation after this address access. For details, please refer to the clause of the chapter of serial interface, and the electrical property of a SPI format. (Note) The change of this register needs OSC frequency or CLKIO external input frequency. Please set "Address 01H" or "Address 21H" before the change of this register.

Description of operation

- 1. LED Matrix
- 1-1. Lighting method of dot Matrix It can control 8 x 16 Matrix.

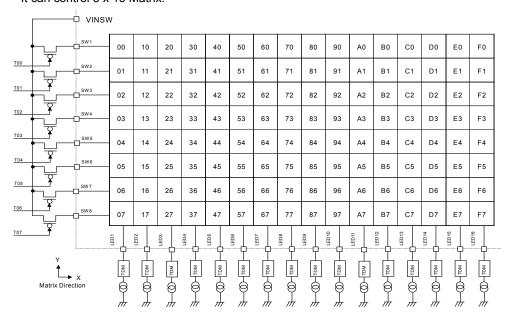


Figure 8. 8 x 16 LED Matrix coordinate

The SW1 – SW8 is turned on by serial. LED is driven one by one within the ON period.

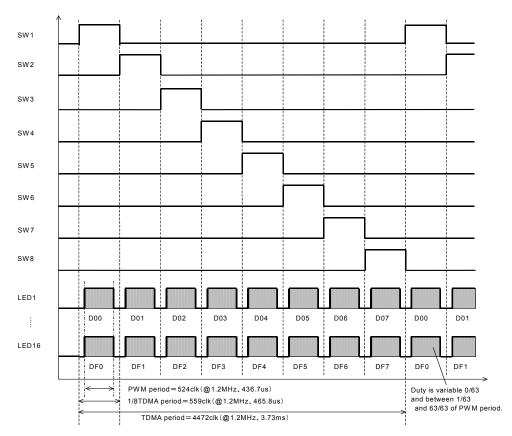


Figure 9. SW timing

1-2. LED lighting example

The following command set is the example of LED matrix lighting.

1) 7Fh	00000000	Select control register
2) 21h	00000000	Select internal OSC for CLK
3) 01h	00001000	Start OSC
4) 11h	11111111	Set LED1-8 enable
5) 12h	11111111	Set LED9-16 enable
6) 20h	00111111	Set Max Duty at Slop Set Max Duty
7) 7Fh	00000001	Select Pattern register to write matrix data
8) 01-40h	XXXXXXX	Write pattern data
9) 7Fh	00000000	Select control register, Pattern register to output for matrix
10) 30h	00000001	Start lighting
11) 30h	00000000	Light off

2. LED Driver Current Control

It can be controlled PWM Duty and DC current for LED driver current.

	Item	Control object	Control detail	Setting Registers	
	item	GOTHIOT OBJECT		Name (Note1)	Bits
(A) ^(Note2)	PWM Duty	Whole matrix	0/63 to 63/63 (64 step)	PWMSET	6
(B) ^(Note3)	DC current	Each matrix dot	0 to 20.00mA (16 step)	ILEDXXSET	4

(Note1) The "XX" shows the matrix number from "00" to "F7". Please refer 8x16 LED Matrix coordinate. (Note2) For setting(A), please refer to P14 :register map of address 20H.

(Note3) For setting(B), please refer to P16 :register map of address 01H-40H.

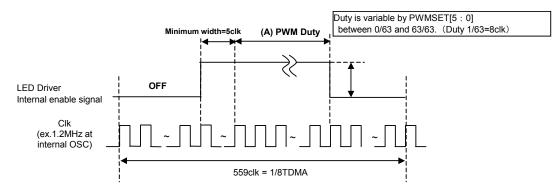


Figure 10. LED output current timing and PWM cycle

524clk of PWM period is set in the 1/8 TDM period (559clk). PWM is operated 63 steps of 8clk. TDM period is 3.73ms (@1.2MHz). Moreover, it has the starting waiting time of a constant current driver by 20clk. PWM"H" time turns into ON time after waiting 20clk. (However, LED driver is set "OFF" compulsorily at PWM=0% setting.)

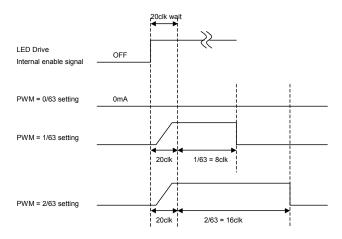


Figure 11. LED output current timing and a PWM cycle

3. About LEDMax current setting

LED Current is variable by RISET resister connecting ISET terminal. Maximum LED current can be leads by next formula.

ILEDmax [A] = $2.0 / RISET [k\Omega]$ (Typ)

Caution that Maximum LED current value is up to 42.5mA.

<ISET terminal resister value vs LED Current (calculation)>

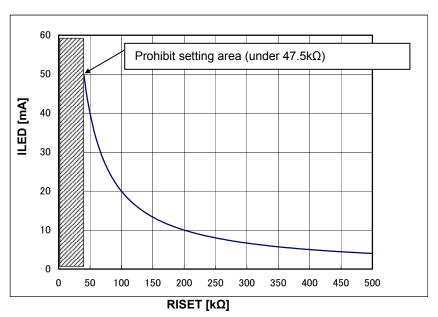


Figure 12. ILED vs RISET

In case of RISET = $100[k\Omega]$, Maximum LED current is 20.0mA.

There are Maximum LED current and Delta LED current value in next table. If you change the RISET value, you can calculate LED current on each step by next table.

Recommended RISET value is $100[k\Omega]$.

In case of RISET under 47.5 [k Ω], ISET short function may be effective.

An example for setting DC current=16mA, PWMDuty=50.8%

- 1. ILEDMax current setting (set by external resistor): RISET= $100k\Omega$ -> ILEDmax[A]= 2.0 / RISET [$k\Omega$]=20mA.
- 2. DC current setting (set by register/Each matrix dot can be set): ILEDxxSET[3:0]="1100" -> ILEDxx[A]=12/15 * ILEDmax=16mA. Please refer to P16 to set register of address01H-40H.
- 3. PWM duty setting (set by register /whole matrix): PWMSET[5:0]="100000" (50.8%) -> ILEDxx[A]=16mA * 50.8%=8.128mA. Please refer to P14 to set register of address20H.
- 4. 1/8TDM active -> ILEDxx[A]=8.128mA * 1/8=1.016mA.

For this case, average 1.016mA LED current is loaded to one LED.

4. Power up sequence

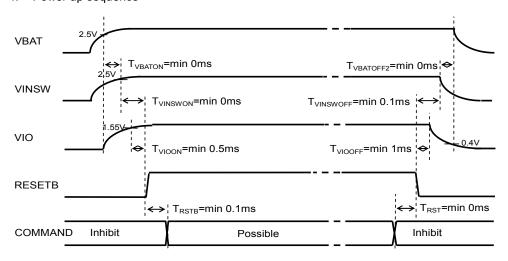


Figure 13. Power up sequence

Please take sufficient wait time for each Power/Control signal.

However, if VBAT<2.1V(Typ) or Ta $>T_{TSD}$ (Typ:175°C), the command input is not effective because of the protection operation

Reset

There are two kinds of reset, software reset and hardware reset

(1) Software reset

- · All the registers are initialized by SFTRST="1".
- · SFTRST is an automatically returned to "0". (Auto Return 0).

(2) Hardware reset

- It shifts to hardware reset by changing RESETB pin "H" \rightarrow "L".
- The condition of all the registers under hardware reset pin is returned to the Initial Value, and it stops accepting all address.
 - All LED driver turn off.
- It's possible to release from a state of hardware reset by changing RESETB pin "L" → "H".
 RESETB pin has delay circuit. It doesn't recognize as hardware reset in "L" period under 5µs.

6. Thermal shutdown

A thermal shutdown function is effective at all blocks of those other than VREF. Return to the state before detection automatically at the time of release.

7. UVLO Function (VBAT Voltage Low-Voltage Detection)

UVLO function is effective at all blocks of those other than VREF, and when detected, those blocks function is stopped. Return to the state before detection automatically at the time of release.

8. I/O

When the RESETB pin is Low, the input buffers (SDA and SCL) are disabling for the Low consumption power.

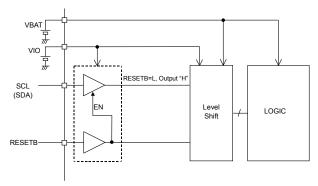


Figure 14. Input disabling by RESETB

9. Standard Clock Input and Output

It is possible to carry out synchronous operation of two or more ICs using the input-and-output function of a standard clock.

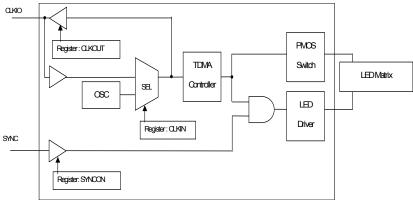


Figure 15. I/O part equivalent circuit diagram

- When a clock is supplied from the exterior
 Inputting an external standard clock from CLKIN and setting register CLKIN=1, IC operates with the clock
 inputted from CLKIN as a standard clock.
- When the built-in oscillation circuit of one IC is used
 When a clock cannot be supplied from the exterior, it is possible to synchronize between ICs by the connection as the following figure.

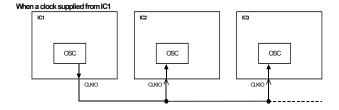


Figure 16. It is an example of application for the usage of two or more.

10. External ON/OFF Synchronization (SYNC Terminal)

Lighting of LED that synchronized with the external signal is possible.

By setting H/L of SYNC terminal, LED drivers output is set ON/OFF.

It's asynchronous operation with the internal TDMA control.

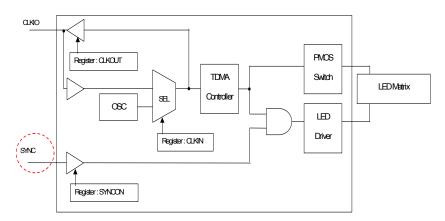


Figure 17. I/O part equivalent circuit diagram

11. About terminal processing of the function which is not used

Please set up a test terminal and the unused terminal as the following table.

Especially, if an input terminal is not fixed, it may occur the unstable state of a device and the unexpected internal current.

Terminal name	Processing	Reason
SYNC	GND Short	In order to avoid an unfixed state.
CLKIO	Open	Pin is fixed to L because pin is connected with a Pull down register of 500Kohm
TEST1	GND Short	The input terminal for a test (94k Ω Pull down)
TESTO	Open	The output terminal for a test
LED Terminal	GND Short	In order to avoid an unfixed state. (Register setup in connection with LED terminal that is not used is forbidden.)
SW Terminal	VINSW Short	In order to avoid an unfixed state. (Register setup in connection with SW terminal that is not used is forbidden.)

12. Setting about VINSW

VINSW is Power Supply about LED Current. It needs proper Voltage range of LED terminal to get proper LED Current (refer to Page5). If it needs the voltage range, it needs to set up proper Voltage range of VINSW which is Power Supply about LED.

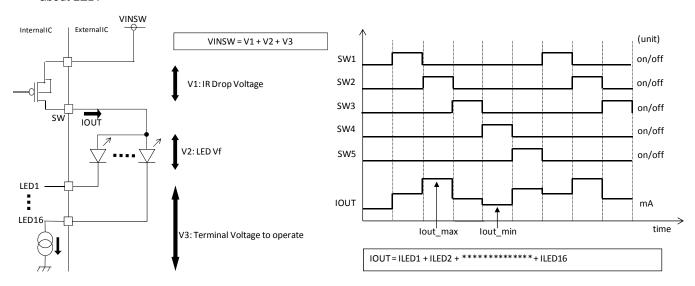


Figure 18. Set up VINSW

Figure 19. SW timing and IOUT

VINSW's Voltage range is made by V1, V2, V3. (refer to Figure 18)

```
VINSW_max = V1_min + V2_min + V3_max
VINSW min = V1 max + V2 max + V3 min
```

V1:IR Drop Voltage

V1 is IR Voltage drop by SW's Resistor at ON and IOUT which is the sum of every LED Current. It is V1's maximum and minimum that it multiplies by SW's Resistor at ON and IOUT maximum and minimum in each SW timing. Please estimate IOUT by setting application. (refer to figure 19). Please refer to page 5 about SW's Resistor at ON. (And it needs to estimate parasitic resistor on PCB's current route).

```
V1_max = Ron * Iout_max
V1_min = Ron * Iout_min
```

V2: LED Vf

V2 is the Voltage drop by LED's Vf. Please confirm about all LED's Vf.

V2_max = Vf_max V2_min = Vf_min

V3: Terminal Voltage to operate

V3 is the terminal Voltage to operate LED Current. (refer to page 5). The minimum is made by IC's ability. The maximum is made by VBAT's minimum in Voltage range.

```
V3_max = VBAT_min - 1.4V
V3 min = 0.2V
```

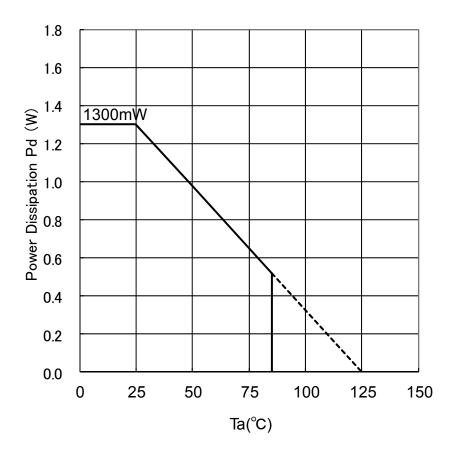
-- Example of Setting VINSW-

Condition: VBAT=3.2 – 4.0 V, lout_max = 100mA, lout_min = 20mA, Vf_max = 3.0V, Vf_min = 2.5V

```
VINSW_max = 0.02V + 2.5V + 1.8V = 4.32V
VINSW_min = 0.1V + 3.0V + 0.2V = 3.3V
```

This is proper Voltage range about VINSW.

Power dissipation (On the ROHM's standard one layer board)



<Calculator>

P_d=(VINSW-V_f) x I_{LED} x N(Channel) ex)

VIŃSW=5V, Vf=3.2V, I_{LED} =20mA,N=16channel, P_d =(5-3.2) x 20 x 16=576mW

Please adjust VINSW and I_{LED} in order to prevent P_d from exceeding 1300mV of power dissipation.

*VINSW: VINSW input voltage

*V_f: Diode V_f
*I_{LED}: LED Current
*N(Channel): LED Channel

Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. The absolute maximum rating of the Pd stated in this specification is when the IC is mounted on a 70mm x 70mm x 1.6mm glass epoxy board. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

Operational Notes - continued

11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

12. Regarding the Input Pin of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode.

When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

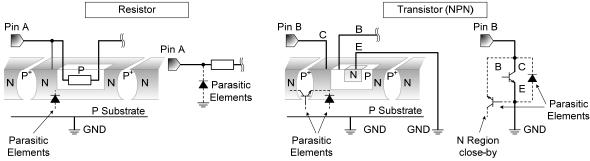


Figure 20. Example of monolithic IC structure

13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

14. Area of Safe Operation (ASO)

Operate the IC such that the output voltage, output current, and power dissipation are all within the Area of Safe Operation (ASO).

15. Thermal Shutdown Circuit(TSD)

This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's power dissipation rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF all output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

16. Over Current Protection Circuit (OCP)

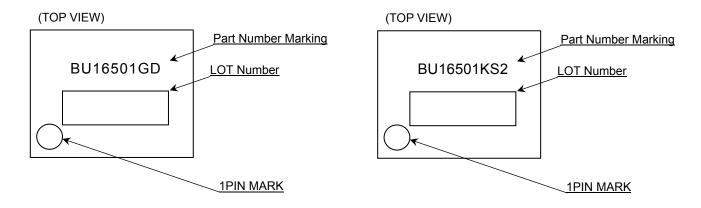
This IC incorporates an integrated overcurrent protection circuit that is activated when the load is shorted. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation or transitioning of the protection circuit.

17. Disturbance light

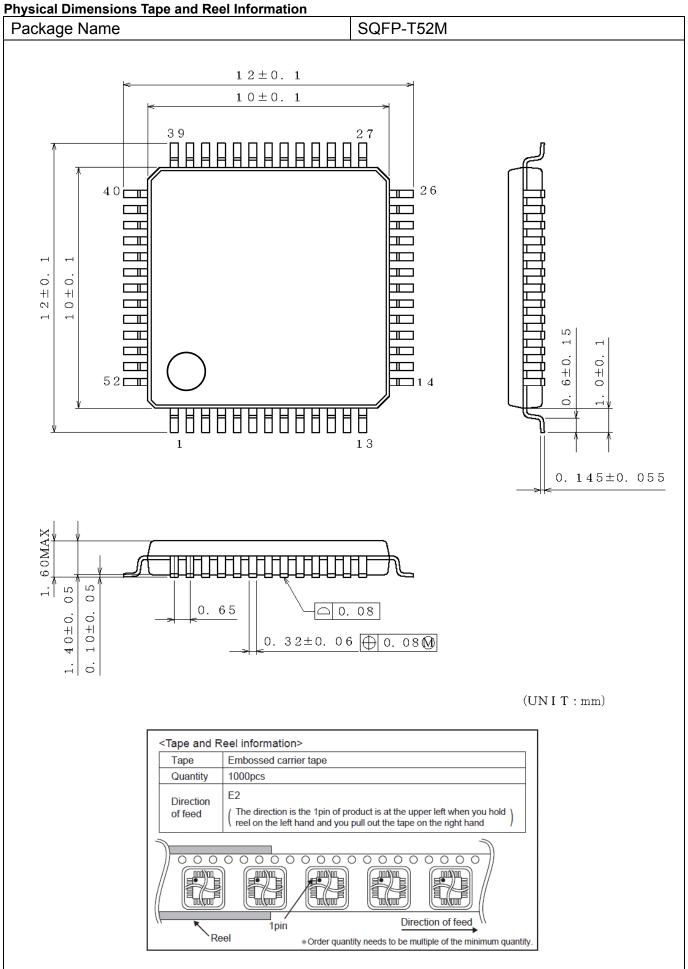
In a device where a portion of silicon is exposed to light such as in a WL-CSP, IC characteristics may be affected due to photoelectric effect. For this reason, it is recommended to come up with countermeasures that will prevent the chip from being exposed to light.

Ordering Information 1 S 5 0 K 2 В U 1 6 E 2 Part Number Packaging and forming Package specification E2: Embossed tape and reel KS2: SQFP-T52M SQFP-T52

Marking Diagram



Marking	Package	Wire
BU16501GD	SQFP-T52M SQFP-T52	Au
BU16501KS2	SQFP-T52	Cu



Physical Dimension, Tape and Reel Information SQFP-T52 Package Name 12. 0 ± 0.3 10. 0 ± 0 . 2 40 💷 0 က +0 0 ± 0 0 0 12. Ш Ш 52 III 14 o 0.125 ± 0.1 (UNIT: mm) 1 ± 0 . PKG: SQFP-T52 0. 3 ± 0.1 0.65 □ 0. 15 Drawing No. B0033 0 <Tape and Reel information> Embossed carrier tape Tape 1000pcs Quantity E2 Direction The direction is the 1pin of product is at the upper left when you hold \ of feed reel on the left hand and you pull out the tape on the right hand Direction of feed 1pin *Order quantity needs to be multiple of the minimum quantity.

Revision History

Date	Revision	Changes	
01.Oct.2013	001	New Release	
04.Sep.2014	002	Additional SQFP-T52 package and marking image	
14.Mar.2016	003	Modified the marking	

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(Note1) Medical Equipment Classification of the Specific Applications

JÁPAN	USA	EU	CHINA
CLASSⅢ	CL ΛCC.π	CLASS II b	CL ACCIII
CLASSIV	CLASSⅢ	CLASSⅢ	CLASSⅢ

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 - [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
 - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
 - [f] Sealing or coating our Products with resin or other coating materials
 - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
 - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation depending on ambient temperature. When used in sealed area, confirm that it is the use in the range that does not exceed the maximum junction temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
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Precaution for Mounting / Circuit board design

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- 2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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- 1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
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 - [b] the temperature or humidity exceeds those recommended by ROHM
 - [c] the Products are exposed to direct sunshine or condensation
 - [d] the Products are exposed to high Electrostatic
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- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- 4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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