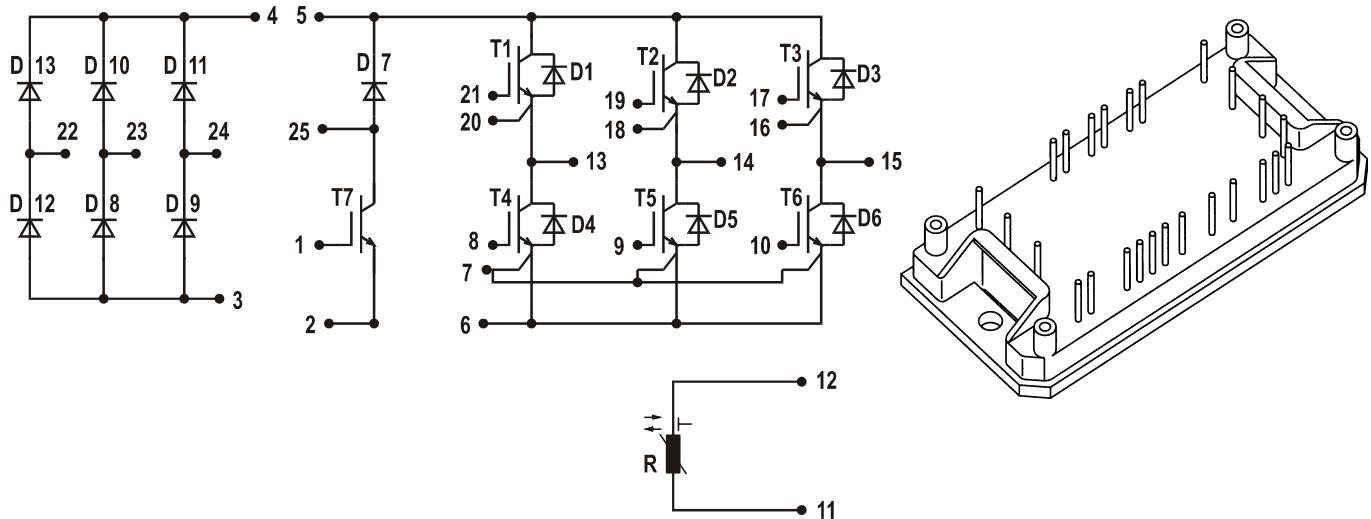


Converter - Brake - Inverter Module (CBI1)



Rectifier	Brake	Inverter
$V_{RRM} = 1200V$	$V_{CES} = 600 V$	$V_{CES} = 600 V$
$I_{FAVM} = 11 A$	$I_{C25} = 7 A$	$I_{C25} = 7 A$
$I_{FSM} = 250 A$	$V_{CE(sat)} = 2.0 V$	$V_{CE(sat)} = 2.0 V$

Input Rectifier Bridge D8 - D13

Symbol	Conditions	Maximum Ratings	
V_{RRM}		1200	V
I_F	$T_{VJ} = 25^\circ C$	36	A
I_{FAVM}	$T_{VJ} = 150^\circ C; T_K = 70^\circ C$	11	A
I_{FSM}	$T_{VJ} = 45^\circ C; t = 10 \text{ ms sine } 50 \text{ Hz}$	250	A
i^2t	$T_{VJ} = 125^\circ C$	310	A^2s
T_{VJ}		+150	$^\circ C$

Symbol	Conditions	Characteristic Values		
		($T_{VJ} = 25^\circ C$, unless otherwise specified)	min.	typ.
I_R	$V_{RRM} = 1200 V; T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		10	μA
			3	mA
V_F	$I_F = 36 A$		1.15	1.4
R_{thJC}	per die		1.4	$^\circ C/W$

Features

- NPT IGBT technology
Square RBSOA, no latchup
- Free wheeling diodes with Hiperfast and soft recovery behaviour
- Isolation voltage 2500 V~
- Built in temperature sense
- High level of integration:
one module for complete drive system
- Direct Copper Bonded Al_2O_3 ceramic base plate

Applications

- AC motor control
- AC servo and robot drives

Advantages

- No need of external isolation
- Easy to mount with two screws
- Package designed for wave soldering
- High temperature and power cycling capability

IXYS reserves the right to change limits, test conditions and dimensions.

Output Inverter T1 - T6, D1 - D6

Symbol	Conditions	Maximum Ratings		
V_{CES}	T _{VJ} = 25°C	600		V
V_{CGR}	T _{VJ} = 25°C; R _{GE} = 20kΩ	600		V
V_{GE}	T _{VJ} = 25°C	±20		V
I_C	T _C = 25°C	7		A
	T _C = 90°C	4.5		A
I_{CM}	t _p = 1 ms = 1% duty cycle; T _C = 25°C	14		A
	T _C = 90°C	9		A
t_{sc}	IGBT V _{CE} = 600 V; T _{VJ} = 125°C non-repetitive	10		μs
P_{tot}	T _C = 25°C	38		W
T_{VJ}	Free-Wheeling Diode	+150		°C
T_{VJ}	IGBT	+150		°C

Symbol	Conditions	Characteristic Values		
		(T _{VJ} = 25°C, unless otherwise specified)		
		min.	typ.	max.
I_{CES}	V _{GE} = 0 V; V _{CE} = 600 V		10	μA
I_{GES}	V _{CE} = 0 V; V _{GE} = 25 V		100	nA
V_{GE(th)}	V _{GE} = V _{CE} ; I _C = 0.2 mA	3	4	5 V
V_{(BR)CES}	V _{GE} = 0 V; I _C = 0.5 mA; T _{VJ} = -40°C	600		V
V_{CE(sat)}	V _{GE} = 15 V; I _C = 4 A; T _{VJ} = 25°C T _{VJ} = 150°C	2.0 2.3	2.5 2.8	V
t_f t_r t_{d(on)} t_{d(off)} E_{off} E_{on}	Inductive load, T _{VJ} = 150°C V _{CC} = 400 V; I _C = 4 A R _G = 50 Ω; V _{GE} = ±15 V	100 20 20 260 0.1 0.2	150 30 30 390 0.13 0.26	ns ns ns ns mJ mJ
C_{iss} C_{oss} C_{rss}	V _{GE} = 0 V V _{CE} = 25 V f = 1 MHz	270 30 18	340 40 23	pF
g_{fs}	V _{CE} = 20 V; I _C = 4 A	0.8	3.2	S
Q_g	V _{CC} = 400 V; I _C = 6 A pulse; V _{GE} = 15 V	24		nC
V_F	I _F = 10 A; V _{GE} = 0 V; T _{VJ} = 25°C T _{VJ} = 150°C	2 1.8		V
t_{rr}	I _F = 10 A; V _R = -300 V; V _{GE} = 0 V di _F /dt = -350 A/μs; T _{VJ} = 100°C	0.2		μs
Q_r	I _F = 10 A; V _R = -300 V; T _{VJ} = 25°C di _F /dt = -350 A/μs; V _{GE} = 0 V; T _{VJ} = 125°C	0.3 0.9		μC
I_r			250	μA
R_{thJC}	IGBT (per die) Diode (per die)	2.7 2.3		°C/W °C/W

Brake Chopper T7, D7

Symbol	Conditions	Maximum Ratings		
V_{CES}	$T_{VJ} = 25^\circ C$	600		V
V_{CGR}	$T_{VJ} = 25^\circ C; R_{GE} = 20k\Omega$	600		V
V_{GE}	$T_{VJ} = 25^\circ C$	± 20		V
I_c	$T_c = 25^\circ C$ $T_c = 90^\circ C$	7 4.5		A
I_{CM}	$t_p = 1 \text{ ms} = 1\% \text{ duty cycle}; T_c = 25^\circ C$ $T_c = 90^\circ C$	14 9		A
t_{sc}	IGBT $V_{CE} = 600 V; T_{VJ} = 125^\circ C$ non-repetitive	10		μs
P_{tot}	$T_c = 25^\circ C$	38		W
T_{VJ}	Free-Wheeling Diode	+150		$^\circ C$
T_{VJ}	IGBT	+150		$^\circ C$

Symbol	Conditions	Characteristic Values		
		($T_{VJ} = 25^\circ C$, unless otherwise specified)	min.	typ.
I_{CES}	$V_{GE} = 0 V; V_{CE} = 600 V$		20	μA
I_{GES}	$V_{CE} = 0 V; V_{GE} = 25 V$		100	nA
$V_{GE(th)}$	$V_{GE} = V_{CE}; I_c = 0.2 \text{ mA}$	3	4	V
$V_{(BR)CES}$	$V_{GE} = 0 V; I_c = 0.5 \text{ mA}; T_{VJ} = -40^\circ C$	600		V
$V_{CE(sat)}$	$V_{GE} = 15 V; I_c = 4 A; T_{VJ} = 25^\circ C$ $T_{VJ} = 150^\circ C$	2.0 2.3	2.5 2.8	V
t_f t_r $t_{d(on)}$ $t_{d(off)}$ E_{off} E_{on}	Inductive load, $T_{VJ} = 150^\circ C$ $V_{CC} = 400 V; I_c = 4 A$ $R_G = 50 \Omega; V_{GE} = \pm 15 V$	100 20 20 260 0.1 0.2	150 30 30 390 0.13 0.26	ns ns ns ns mJ mJ
C_{iss} C_{oss} C_{rss}	$V_{GE} = 0 V$ $V_{CE} = 25 V$ $f = 1 \text{ MHz}$	270 30 18	340 40 23	pF
g_{fs}	$V_{CE} = 20 V; I_c = 4 A$	0.8	3.2	S
Q_g	$V_{CC} = 400 V; I_c = 6 A \text{ pulse}; V_{GE} = 15 V$	24		nC
V_F	$I_F = 10 A; V_{GE} = 0 V; T_{VJ} = 25^\circ C$ $T_{VJ} = 150^\circ C$	2 1.8		V
t_{rr}	$I_F = 10 A; V_R = -300 V; V_{GE} = 0 V$ $di_F/dt = -350 A/\mu s; T_{VJ} = 100^\circ C$	0.2		μs
Q_r	$I_F = 10 A; V_R = -300 V; T_{VJ} = 25^\circ C$ $di_F/dt = -350 A/\mu s; V_{GE} = 0 V; T_{VJ} = 125^\circ C$	0.3 0.9		μC
I_r			250	μA
R_{thJC}	IGBT (per die) Diode (per die)	2.7 2.3		$^\circ C/W$

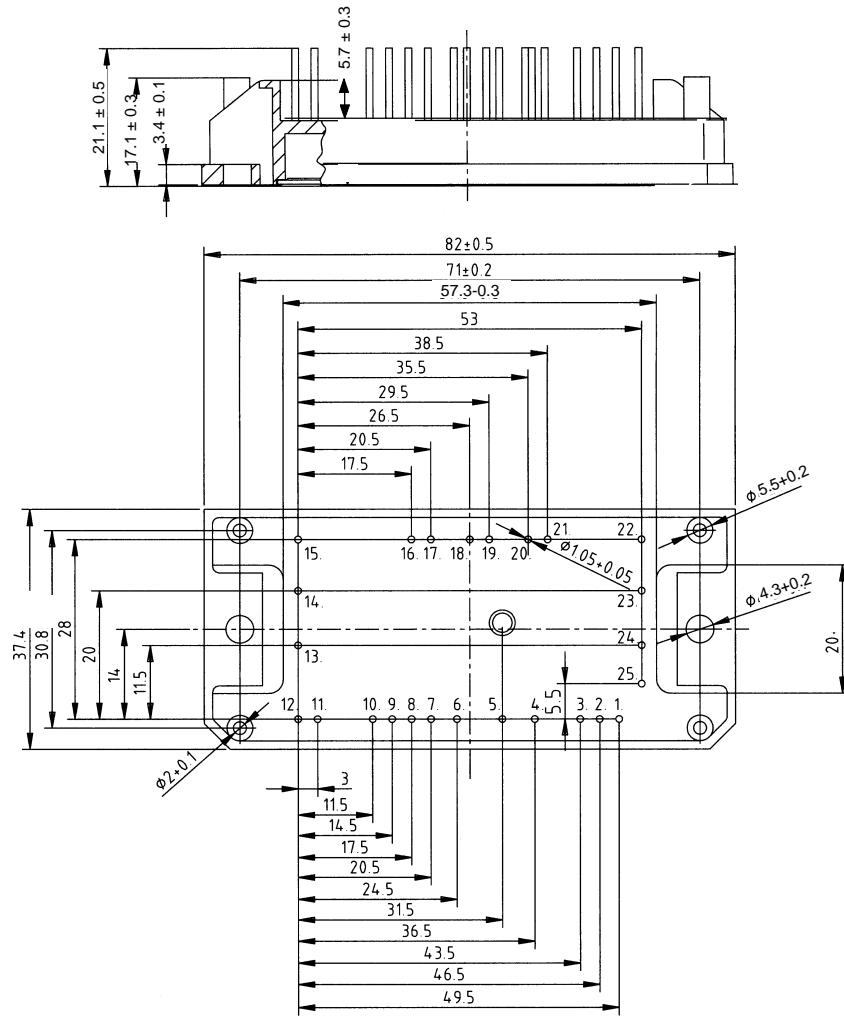
Module

Symbol	Conditions	Maximum Ratings	
T_{stg}		-40...+125	°C
V_{ISOL}	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}; t = 1 \text{ min}$	2500	V~
M_d	Mounting torque (M4)	2.0 - 2.2 18 - 20	Nm lb.in.
d_s	Creepage distance on surface	12.7	mm
d_A	Strike distance in air	12.7	mm
Weight	typ.	42	g

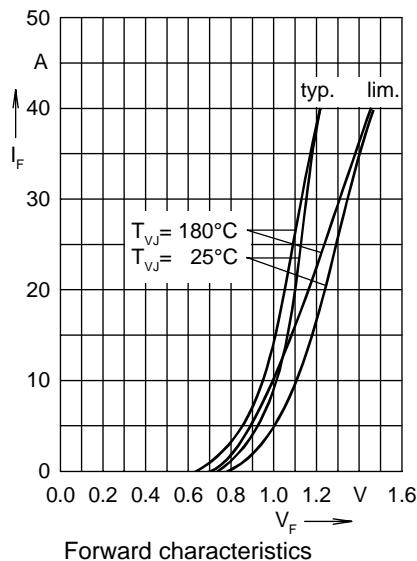
Temperature Sensor R

Symbol	Conditions	Maximum Ratings	
R	$T_{amb} = 20^\circ\text{C}$	4.7	kΩ

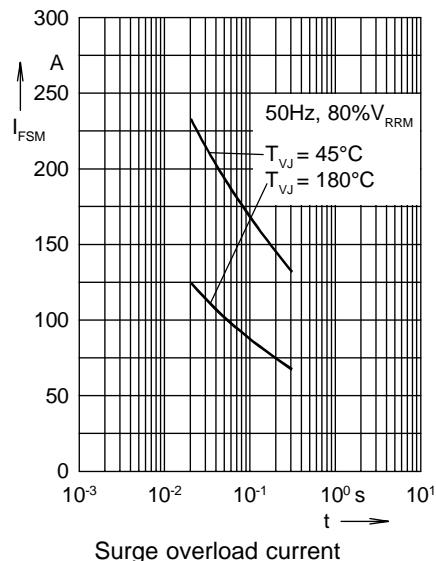
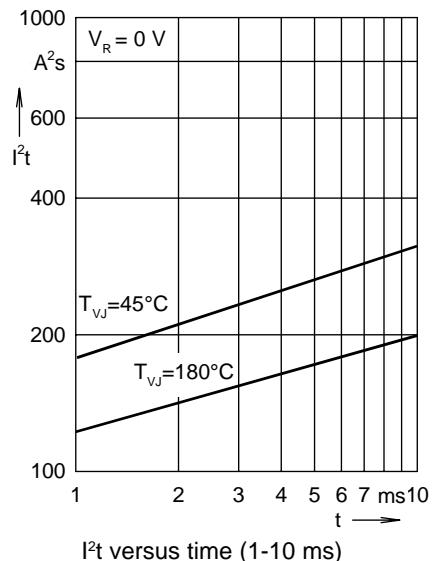
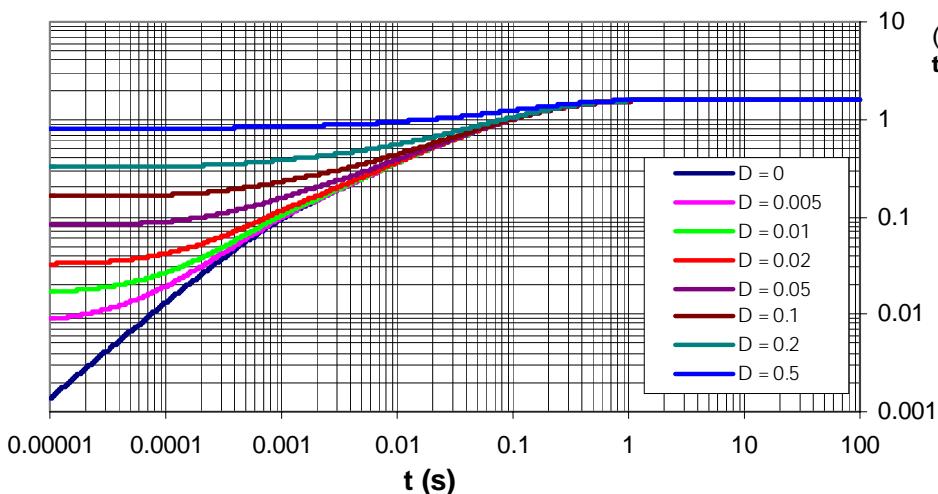
For additional data see C620/4.7k 5% S+M NTC thermistor catalog

Dimensions in mm (1 mm = 0.0394")

Input Rectifier Bridge D8 - D13



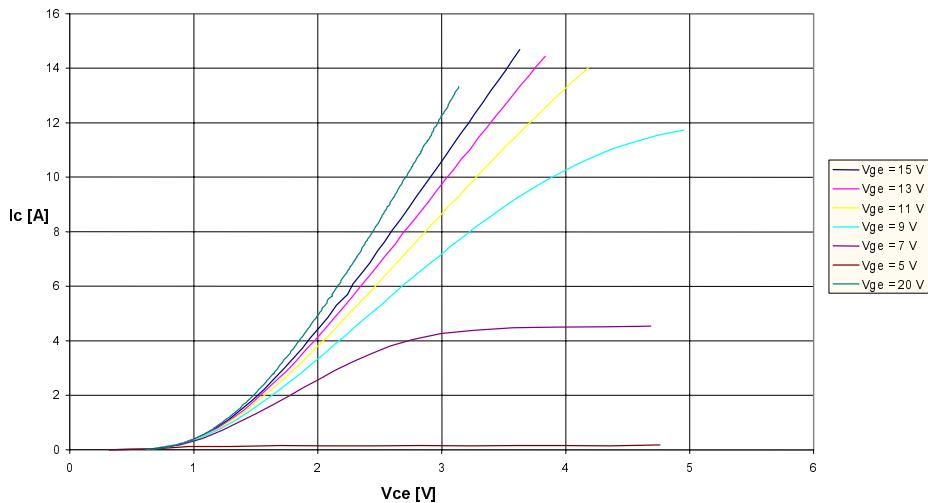
Forward characteristics

Surge overload current
 I_{FSM} : crest value, t : duration I^2t versus time (1-10 ms)

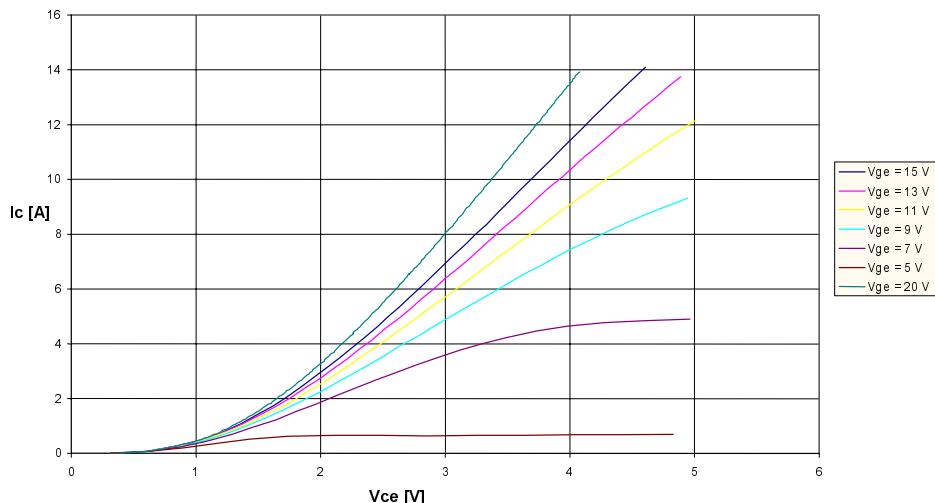
Transient thermal resistance junction to heatsink

Output Inverter T1 - T6, D1 - D6

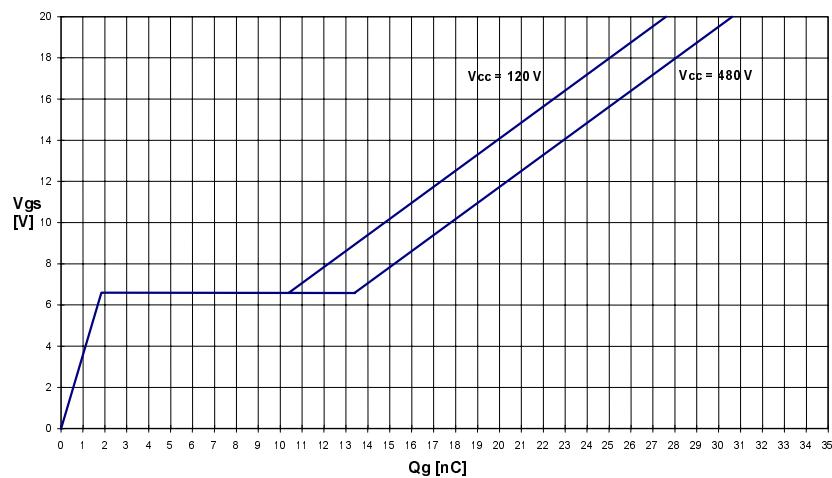
Typ. Output characteristics, 25°C



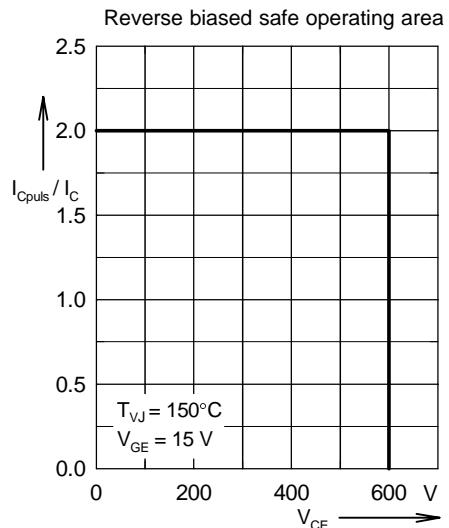
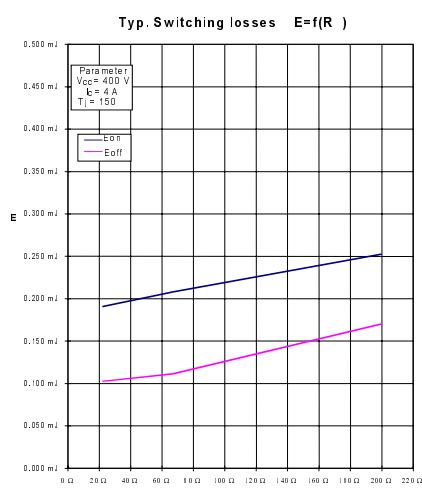
Typ. Output characteristics, 125°C



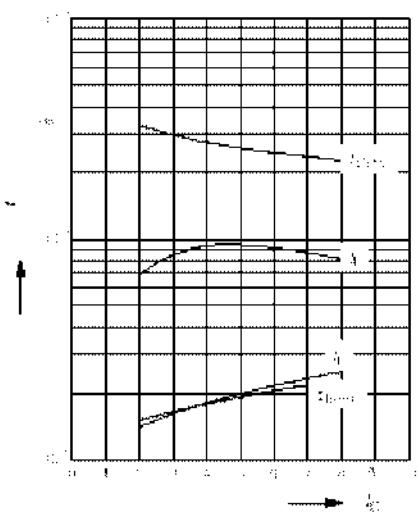
Typ. Gate-Charge



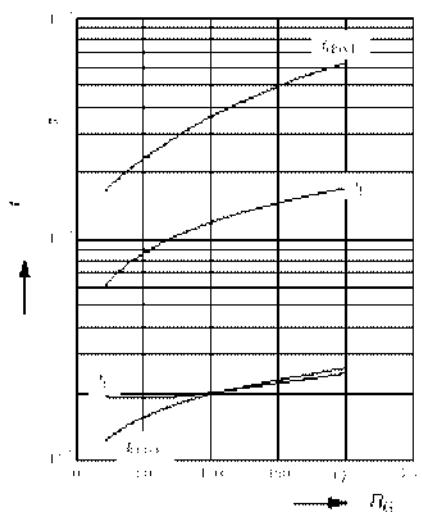
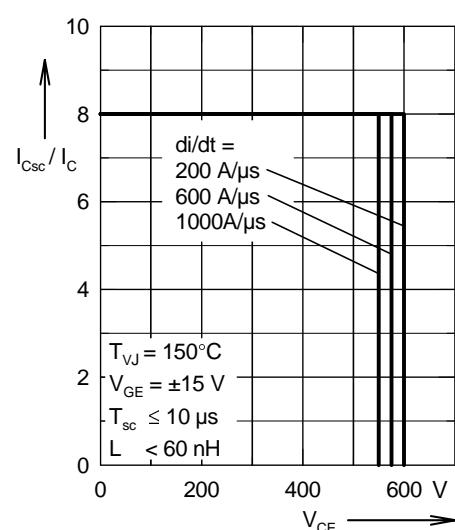
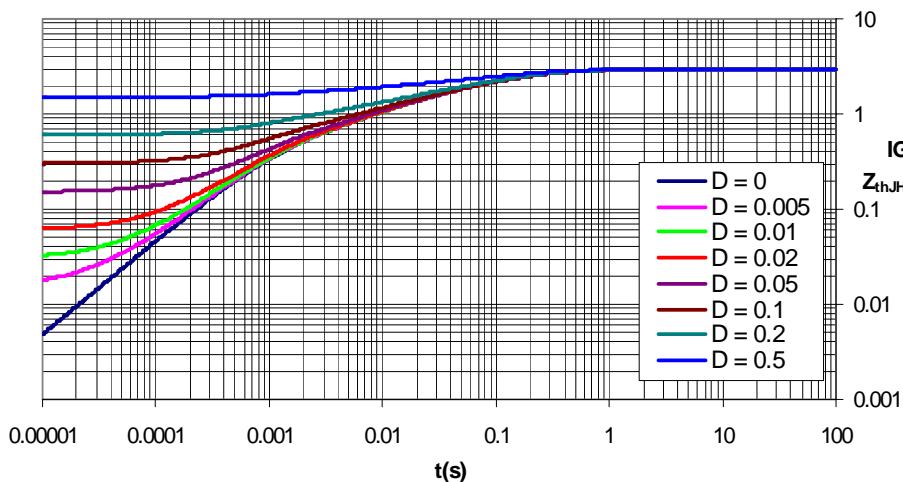
Output Inverter T1 - T6, D1 - D6


Typ. switching time

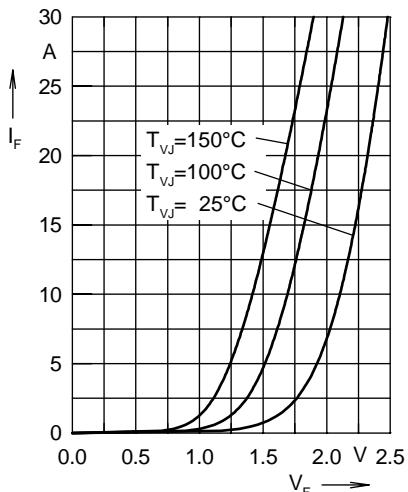
t_{on}/t_{off} inductive load, $T_j = 150^\circ\text{C}$
par. $V_{GE} = 400 \text{ V}$, $V_{GL} = 0 \pm 15 \text{ V}$, $R_G = 67 \Omega$


Typ. switching time

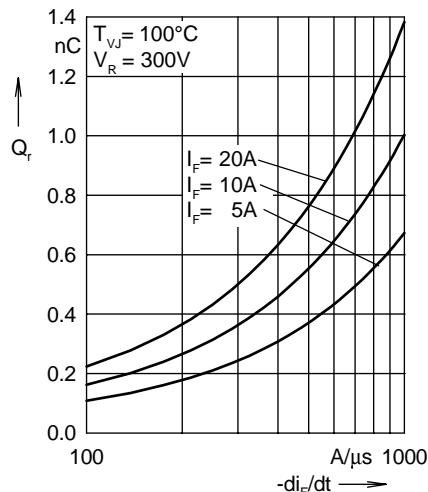
t_{on}/t_{off} inductive load, $T_j = 150^\circ\text{C}$
par. $V_{GE} = 400 \text{ V}$, $V_{GL} = 0 \pm 15 \text{ V}$, $Q_L = 2 \text{ A}$


Short circuit safe operating area

Transient thermal resistance junction to heatsink


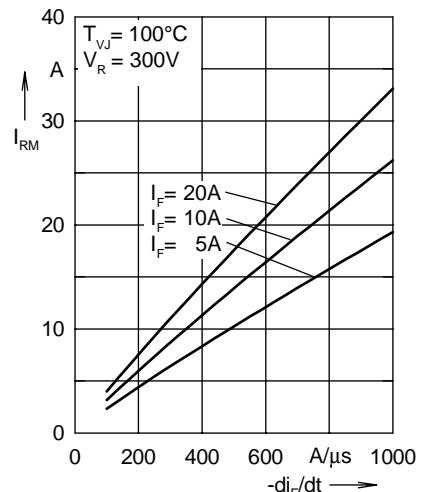
Output Inverter D1 - D6



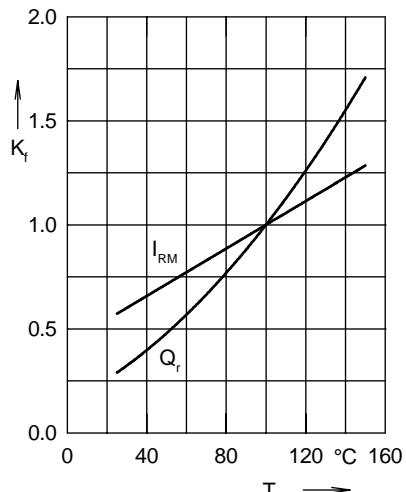
Forward current I_F versus V_F



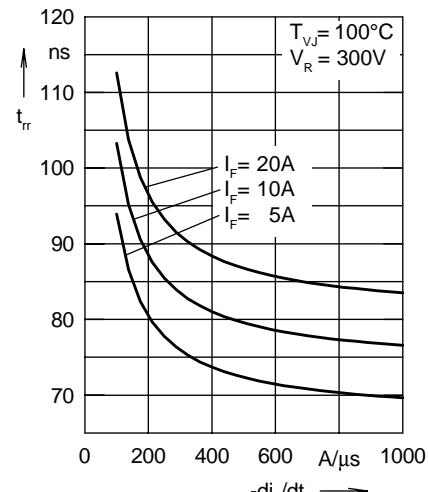
Reverse recovery charge Q_r versus $-di_F/dt$



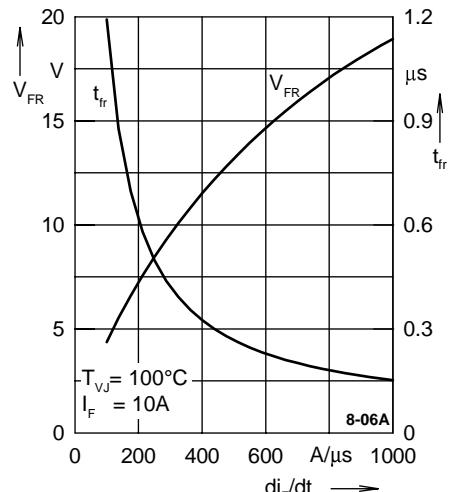
Peak reverse current I_{RM} versus $-di_F/dt$



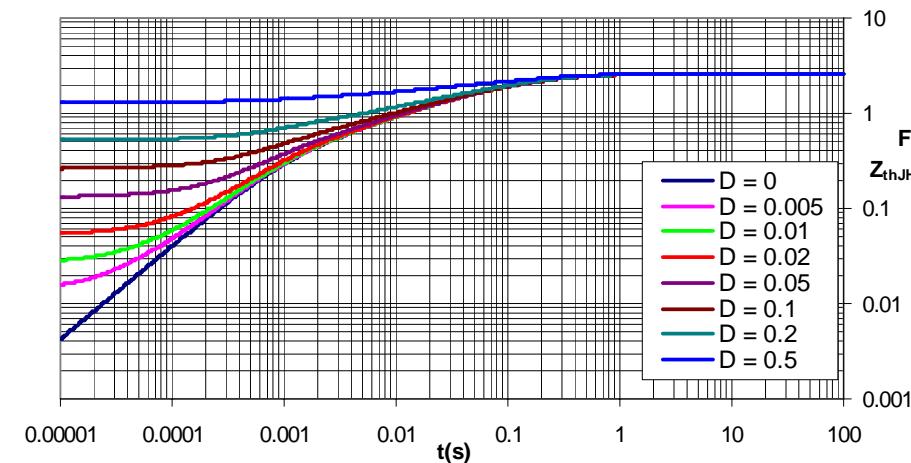
Dynamic parameters Q_r , I_{RM} versus T_{VJ}



Recovery time t_{rr} versus $-di_F/dt$



Peak forward voltage V_{FR} and t_{rr} versus di_F/dt



Transient thermal resistance junction to heatsink